

# PSDL Series Servo Drive



## Product Features

### High Efficiency

- Built-in gantry control synchronization algorithm
- Automatic determination of load inertial mechanical properties, setting optimal gain and shortening system commissioning time
- Powerful internal location control mode, 32 sets of location data path planning. This feature not only saves the user PLC costs, but also allows for more efficient control

### High Accuracy

- Bus synchronization accuracy <0.1us: multi-axis synchronization algorithm at current loop level

### Stable

- Mechanical resonance frequency analysis, configured with two sets of trap filters, adjustable frequency (50 ~ 5000Hz) and trap depth effectively overcome low frequency resonance and mechanical end vibration, vibration frequency (1 ~ 100Hz) and vibration damping can be set
- Frictional torque compensation reduces the effect of static friction during mechanical commutation and improves command following performance at low speeds

### Easy to Operate

- Support for debugging software, mechanical characteristics analysis, parameter setting, monitoring and other functions, intuitive and simple operation

## Specifications

### Model

PSDLAD08□□ PSDLAD15□□  
0.75KW 1.5KW

### Input Power

#### Control Mode

Three-phase PWM converter sine wave drive

#### Main Power

Single-phase / three-phase 220V AC (-15~+10%, 50~60Hz)

#### Control Power

Single-phase 220V AC (-15~+10%, 50~60Hz)

#### Rated Current

220V: 0.75kW/5.5A, 1.5kW/10A

#### Encoder Feedback

ABZ incremental encoder/absolute encoder

### Environment

#### Working Temperature

0~45°C

#### Storage Temperature

-20~65°C

#### Working Humidity

20~85%RH or less (non condensing)

#### Storage Humidity

20~85%RH or less (non condensing)

#### Working And Storage air

Indoor (no direct sunlight), non-corrosive gases, flammable gases, oil mist, dust

#### Altitude

Below 1000m

#### Vibration

5.8m/s<sup>2</sup> (0.6G) below 10~60Hz (Cannot be used continuously at resonant frequency)

#### Insulation And Pressure Resistance

Primary- between F and G, 1 minute under AC1500V

### Functions

#### IO Input

6-channel (DC24V opto-coupler isolation) Input function can be selected according to parameters below: Servo on, P action positive rotation inhibit, negative rotation inhibit, alarm reset, positive torque limit, negative torque limit, error clear

#### IO Output

4-channel opto-coupler isolated output; the following output function can be selected according to parameters: Alarm output, position proximity, velocity consistent detection output, motor rotation detection, servo ready, torque limit, brake release

#### Pulse Input

Differential input: 500K; open collector: 200K  
Pulse + direction, AB orthogonal pulse, CW+CCW pulse

#### Pulse Output

Phase A, phase B: differential output. Phase Z: differential output or open collector output

#### Internal Speed Command

Three-speed distribution via input terminals

#### Overload Capacity

Max. 3 times torque

#### Analog Input

2-channel differential input ±10V, 1-channel single-ended 0-10V; switch according to control mode

#### Communication

Modbus; Customized CAN

#### Control Modes

12 control modes: position control, speed control, torque control, inner speed, position/speed control, position/torque control, speed/torque control, inner speed/position, inner speed/speed, inner speed/torque, speed/zero clamp, position control/command inhibit

#### Regenerative Resistance

400W: without external regenerative resistance; over 750W: with